# Generalized Deng Entropy

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## Abstract

Dempster-Shafer evidence theory as an extension of Probability has wide applications in many fields. Recently, A new entropy called Deng entropy was proposed in evidence theory. Deng Entropy as an uncertain measure in evidence theory. Recently, some scholars have pointed out that Deng Entropy does not satisfy the additivity in uncertain measurements. However, this irreducibility can have a huge effect. In more complex systems, the derived entropy is often unusable. Inspired by this, a generalized entropy is proposed, and the entropy implies the relationship between Deng entropy, Rényi entropy, Tsallis entropy.

*Keywords:* Deng entropy, Rényi entropy, Tsallis entropy. ,Uncertaintity, Dempster shafer evidence theory.

### 1 1. Introduction

Dempster-shafer evidence theory [1, 2] was proposed by Dempster [1] and developed by Shafer [2]. Evidence theory as a framework of uncertain reasoning is closely related to probability theory. It can be considered as a generalization of probability, assigning belief to power set of the propositions rather than single elements. This theory allows for the combination of evidence from different sources and draws a certain degree of conclusion, taking

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into account all available evidence. There are a lot of applications about it
[3, 4, 5, 6, 7, 8].

How to measure uncertainty has always received widespread attention in 10 evidence theory. Most of the measurements on uncertainty are related to 11 Shannon entropy [9]. Yager [10] generalizes the entropy in probability theory 12 to evidence theory. This entropy is based on the belief structure, which 13 provides an indicator of the quality of the evidence. Maeda and Ichihashi 14 [11] propose a uncertain measurement method. This uncertainty consists of 15 two types, one containing the uncertainty of Shannon entropy determination 16 and the other related to the cardinality of the set. 17

Recently, A new entropy named Deng entropy [12] has been proposed 18 to solve uncertain measurement. This entropy is directly related to basic 19 probability assignment. When the belief is assigned to the element of frame 20 of discernment instead of the power set, this entropy is degenerated into 21 the Shannon entropy. Deng entropy quickly attracts the attention of many 22 scholars. Abellán [13] discusses the property of Deng entropy and points out 23 that this entropy could quantify two types of uncertainty in evidence theory. 24 Tang et al. [14] extended Deng entropy to an open world and applied it to 25 information fusion. There are other discussions and applications about Deng 26 entropy [15, 16]. 27

Entropy is diverse [17]. After Clausius [18] proposed the concept of en-28 tropy, various entropies were raised. Rényi [19] proposed an entropy called 29 Rényi entropy. Rényi entropy [19] has many applications in quantum infor-30 mation [20], information theory [21], and fractal theory [22]. Tsallis entropy 31 is a generalization of the standard Boltzmann Gibbs entropy [23]. Tsallis en-32 tropy has been controversial since it was proposed [24]. After many complex 33 systems are derived from Tsallis entropy [25], Tsallis entropy has received a 34 lot of attention. 35

It can be proved that Shannon entropy [9] is a special case of Tsallis entropy [23], Rényi entropy [19]. So a natural question is what is the relationship between Deng entropy [12] and Rényi entropy [19] and Tsallis entropy [23]? Therefore, in order to explore the relationship between Deng entropy [12] and these two entropies. In this paper, we propose two generalized Deng entropies, which reveal the relationship with these entropies.

The structure of this article is as follows. Section 2 introduces some basic
knowledge. Section 3 proposes the generalized Deng entropy. In section 4,
some examples are discussed. Finally, conclusion is given.

#### 45 2. Basic Knowledge

In this section, Deng entropy [12], Rényi entropy [19], Tsallis entropy [23]
will be briefly introduced.

48 2.1. Deng Entropy

<sup>49</sup> Compared to probability theory, Dempster shafer evidence theory [1, 2] <sup>50</sup> has a greater advantage to deal with uncertainty. First, Dempster shafer <sup>51</sup> evidence theory [1, 2] can deal with more uncertainty in the real world. In <sup>52</sup> Dempster shafer evidence theory [1, 2], belief is not only assigned to a single <sup>53</sup> element but also to a multi-element set [26]. In addition, it does not require <sup>54</sup> prior information before combining each individual evidence [27]. Some basic <sup>55</sup> knowledge about evidence theory is introduced.

Suppose the power set of the frame of discernment  $X = \{\theta_1, \theta_2, \dots, \theta_N\}$ is P(X). Where the elements of X are mutually exclusive and exhaustive. For a frame of discernment X, the mass function is defined as follows [2].

$$m: P(X) \mapsto [0,1] \tag{1}$$

<sup>59</sup> where  $m(\phi) = 0$  and  $\sum_{F_i \in P(X)} m(F_i) = 1$ .

In evidence theory, mass function is also called basic probability assignment (BPA), indicating the degree of belief in  $A_i \in P(X)$ .

<sup>62</sup> Deng entropy in evidence theory is difined as follows [12].

$$E_d = -\sum_i m(A_i) \ln \frac{m(A_i)}{2^{|A_i|} - 1}$$
(2)

where  $A_i \in P(X)$  and  $|A_i|$  is the cardinality  $A_i$ .

Note that the base of all log functions is taken as a natural number e. *i.e.*  $\log_e \triangleq \ln$ .

66 2.2. entropy

For a discrete random Y, its probability distribution is  $P_Y = \{p_i | i = 1, 2, ..., N\}$ . Rényi entropy is defined as follows [19].

$$H_{\alpha} = \frac{1}{1-\alpha} \log(\sum_{i} p_{i}^{\alpha}) \tag{3}$$

where  $\alpha \ge 0$ .

#### 70 2.3. Tsallis entropy

Given a discrete Z, its probability distribution is  $P_Z = \{p_i | i = 1, 2, ..., N\}$ . Tsallis entropy is defined as follows [23].

$$H_q = \frac{k}{q-1} \left(1 - \sum_i p_i^q\right) \tag{4}$$

where q and k are parameters. For analysis, k is set to 1, which means that Tsallis entropy can be expressed as follows.

$$H_q = \frac{1}{q-1} (1 - \sum_i p_i^q)$$
 (5)

#### 75 3. Generalized Deng Entropy

In evidence theory, Klir and Wierman define five types of uncertainty 76 requirements: probability consistency, set consistency, range, subadditive, 77 additivity [28]. Are all the uncertain measurements satisfying these five re-78 quirements? Abellán [13] points out that Deng entropy [12] does not satisfy 79 additivity and sub-additiveness. In fact, Tsallis entropy [23] does not satisfy 80 additivity [29]. Rényi pointed out that if the additivity of Rényi entropy [19] 81 is strictly satisfied, then there are only two possible Kolmogorov-Nagumo 82 functions [29]. For example, in some systems involving long range forces 83 [29], this kind of nonlinear system has come to receive widespread attention 84 [30].85

Deng entropy has been proposed as an entropy in the field of information [12], although there is currently no physical explanation. However, this nonadditive nature seems to imply a connection to more complex systems.

#### 89 3.1. *R*-*D* entropy

In order to bridge the relationship between Deng entropy [12] and Rényi entropy [19], a generalized D-R entropy is proposed as follows.

$$E_{\alpha}(m(A_i)) = \frac{1}{1-\alpha} \ln\left[\sum_{i} (\frac{m(A_i)}{2^{|A_i|} - 1})^{\alpha} (2^{|A_i|} - 1)\right]$$
(6)

## <sup>92</sup> Theorem 1. When $\alpha \rightarrow 1$ , D-S entropy degenerates into Deng entropy.

**Proof 1.**  $\lim_{\alpha \to 1} E_{\alpha}(m(A_i))$ 93  $= \lim_{\alpha \to 1} \frac{\frac{\partial}{\partial \alpha} \left[ \ln(\sum_{i} (\frac{m(A_i)}{2^{|A_i|} - 1})^{\alpha} (2^{|A_i|} - 1) \right]}{\frac{\partial}{\partial \alpha} (1 - \alpha)} \\ = \frac{\sum_{i} e^{\alpha \ln(\frac{m(A_i)}{2^{|A_i|} - 1})} (2^{|A_i|} - 1) \ln(\frac{m(A_i)}{2^{|A_i|} - 1})}{-\sum_{i} (\frac{m(A_i)}{2^{|A_i|} - 1})^{\alpha} (2^{|A_i|} - 1)} \\ = \frac{\sum_{i} e^{\alpha \ln(\frac{m(A_i)}{2^{|A_i|} - 1})} (2^{|A_i|} - 1) \ln(\frac{m(A_i)}{2^{|A_i|} - 1})}{-\sum_{i} (\frac{m(A_i)}{2^{|A_i|} - 1})^{\alpha} (2^{|A_i|} - 1)}$ 94

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96 
$$= -\sum_i m(A_i)$$

It can be easily proved that the R-D entropy degenerates into Rényi 97 entropy when the belief is assigned to single elements. Naturally, when  $\alpha \to 1$ 98 and belief is assigned to single elements, the R-D entropy degenerates into 99 Shannon entropy. 100

#### 3.2. T-D Entropy 101

T-D entropy is proposed as follows, which may expose the relationship 102 between Deng entropy [12] and Tsallis entropy [23]. 103

$$E_q(m(A_i)) = \frac{1}{1-q} \left[ 1 - \sum_i \left( \frac{m(A_i)}{2^{|A_i|} - 1} \right)^q (2^{|A_i|} - 1) \right]$$
(7)

**Theorem 2.** When  $q \rightarrow 1$ , T-D entropy degenerates into Deng entropy. 104

105 **Proof 2.** 
$$\lim_{q \to 1} E_q(m(A_i))$$
106 
$$= \lim_{q \to 1} \frac{\frac{\partial}{\partial q} \left[ 1 - \sum_i \left( \frac{m(A_i)}{2^{|A_i|} - 1} \right)^q (2^{|A_i|} - 1) \right]}{\frac{\partial}{\partial q} (q - 1)}$$
107 
$$= -\sum_i e^{q \ln(\frac{m(A_i)}{2^{|A_i|} - 1})} (2^{|A_i|} - 1) \ln(\frac{m(A_i)}{2^{|A_i|} - 1})$$
108 
$$= -\sum_i m(A_i) \ln \frac{m(A_i)}{2^{|A_i|} - 1}$$

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Similarly, it can be proved that the T-D entropy degenerates into Tsallis 109 entropy when the belief is assigned to single elements. Naturally, when  $q \to 1$ 110 and belief is assigned to single elements, the T-D entropy degenerates into 111 Shannon entropy. 112

#### 3.3. R-T-D Entropy 113

Masi [29] proposes a unified entropy that links Rényi entropy [19] and 114 Tsallis entropy [23]. Inspired by him, a unified form of entropy is proposed 115 which could linkRényi entropy [19], Tsallis entropy [23] and Deng entropy 116 [12].117

$$E_{t,r}(m(A_i)) = \frac{1}{1-r} \left[ \left[ \sum_{i} \left( \frac{m(A_i)}{2^{|A_i|} - 1} \right)^t (2^{|A_i|} - 1) \right]^{\frac{1-r}{1-t}} - 1 \right]$$
(8)

It can be proved that when r tends to t, the R-T-D entropy degenerates into T-D entropy. when r tends to 1, the R-T-D entropy degenerates into R-D entropy.

#### 121 **4.** Conclusion

<sup>122</sup> We propose a generalized entropy that links Deng entropy [12], Rényi <sup>123</sup> entropy [19], Tsallis entropy [23].

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