# The theory of electrodynamic space-time relativity (Revision 4)

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**Abstract:** The theory of electrodynamic space-time relativity (TESTR) is the study of the transformation of time and space between two electrodynamic inertial frames of reference, which have both inertial velocity difference and electric potential difference. It is a fundamental space-time theory of theoretical physics based on the Einstein's special theory of relativity (STR), the electric potential limit postulate and the high-precision experimental facts of the inversion proportional square law of Coulomb's force.

It also proposed new basic physical concepts, such as electric potential limit, quaternion velocity, quaternion electric potential and etc. The two basic physical quantities, electric potential and velocity, are unified through the form of quaternions. It revealed the inherent relationships between the quaternion velocity or the quaternion electric potential and space-time. In mathematical form, it starts with the special theory of relativity in the real form and develop into the complex form and then further into the quaternion form. In the physical sense, it expands the special relativity from having an only inertial frame of reference to having both the inertial frame of reference and electric equipotential frame of reference.

This paper discusses in detail the process of establishing the theory of complex electrodynamic space-time relativity and theory of quaternion electrodynamic space-time relativity as well as their various conversions and transformations. With the use of the new concept of system time, it leads to the expression of the fundamental equations of TESTR to be as concise as the form of Galilean transformation. In addition, its content is also more symmetrical and universal. It can correctly derive a set of more complex equations of the special three-dimensional theory of relativity. At the same time, proved that the special theory of relativity is a special case of TESTR, and found another important new special case: the theory of electric potential relativity (TEPR). The basic effects of TESTR were also discussed. It predicts some important new space-time change effects, for example, the electric potential time expansion effect. Such proposed effects would provide some theoretical basis for the experimental validation of TESTR. The appendix of the paper proves mathematically that the basic equations of the theory are consistent with the hypothesis.

**Keyword**: special theory of relativity, postulates of electric potential limit, the theory of electric potential relativity, theory of complex electrodynamic space-time relativity, the theory of quaternion electrodynamic space-time relativity,

#### Part 1. The theory of complex electrodynamic space-time relativity (TCESTR)

Einstein's special theory of relativity (STR) is based on two basic postulates about inertial motion, that is:

- 1. The principle of relativity: physical laws should be the same in every inertial frame of reference
- 2. The principle of invariant speed of light: in any inertial system, the speed of light in the vacuum is a constant. According to these two postulates, the famous Lorentz transform equations can be derived.

$$X' = \gamma(X - V_X t) \tag{1}$$

$$Y' = Y \tag{2}$$

$$Z' = Z \tag{3}$$

$$t' = \gamma \left( t - \frac{V_X}{C_0^2} X \right) \tag{4}$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v_X^2}{C_0^2}}} \tag{5}$$

Here, the Lorentz transformation equations are scalar equations, where  $V_X$  is the speed along the x-axis of inertial frame  $\Sigma_R'(X', Y', Z', t')$  relative to the inertial frame  $\Sigma_R(X, Y, Z, t)$ .  $C_0$  is the speed of light. X, Y, Z, t and X', Y', Z', t' are the length and time of the observing system and the observed system, respectively.

Upon analyzing the basic postulates of the special theory of relativity, a question can be asked: is our understanding of motion complete? Is there another physical reference frame beside the inertial reference frame, where the same the physical laws still hold true in each frame of reference when it is in different states? In this physical reference frame, the state of such reference frame cannot be determined through any experiments. Do the related physical parameters have a limit? And would such limit lead to the relativistic effect of time and space? After further study, it was proposed that equipotential bodies are of such physical reference systems. Based on Coulomb's inverse proportional square law and its high-precision experiments<sup>[1]</sup>, we know that within a closed conductor of any shape, the electric potential at any point is the same regardless of how much electric charge its surface carries. In addition, the interior electric field strength E is zero. This is a corollary of Gauss' law of electric field.

Thus, a thought experiment can be carried out: there are two identical closed metal carriages A and B, and they are motionless relative to each other and are insulated from each other with only carriage B being grounded. Suppose there is an electrode of an ultra-high voltage static electric generator connected to B, and the other electrode is connected to the carriage A. Let the electric potential of the ground be zero. When the electrostatic generator continues to work, the A carriage is charged with lots of charges (either positive or negative) by the generator. The electric potential on the surface and in the interior of the carriage increases with it. When the surface electric charges reach Q, the interior and surface electric potential  $\varphi$  are the same everywhere. At the same time, the electric field intensity is zero. Therefore, when an observer is isolated inside carriage A, it is impossible for the observer to know the values of electric potential or whether it is positive or negative relative to carriage B through any experiment. Same can be said for the observer in the carriage B where the electric potential is zero, even when there is a very high electric potential difference between them. Please note that same experimental results can be obtained in the inertial frames of reference. The principle of relativity is likely to be true in any electric potential frame of reference.

So, is there any limit to the electric potential? According to electromagnetism, the superposition of electric potentials is linear, that is, the electric potential has no limit. And the central electric potential of the ideal point charge is also infinite. Further calculations show that the electric field energy of the point charge is also infinite. Obviously, this is a wrong conclusion and is universally recognized as the difficulty that electromagnetism cannot overcome by itself. In the basic theory of modern physics, the issue of point charge energy dissipation is ubiquitous. If the limit of electric potential exists, then the electromagnetics must be modified accordingly – the point charge center electric potential is finite, and its electric field energy is likely not to diverge, thus overcoming the theoretical difficulties in electromagnetism. There is not any the physical experiment that shows that the electric potential cannot has a limit. Therefore, the postulate of the electric potential limit is reasonable.

In summary, two postulates of equipotential reference system can be put forth:

- 3. The relative principle of electric potential: the physical law has the same form in any electric equipotential frame of reference;
- 4. The postulate of electric potential limit: in any stationary and equipotential frame of reference, the electric potential limit is a constant  $\Phi_0$  at any point in the vacuum.

The value for such electric potential limit  $\Phi_0$  can only be determined by experiment. In the Planck's units, Planck voltage is a very large value of  $1.04295 \times 10^{27}$  volts. It could be used as one of the reference values of the electric potential limit  $\Phi_0$ .

By comparing the relative principle of electric potential and the postulate of electric potential limit with the two postulates of the special theory of relativity, it can be seen that their forms are very similar. When the two postulates are established, then, the current Maxwell's equation must be modified. The superposition of the electric potential will be non-linear, and many physical parameters are likely to have functional relations with the electric potential of the frame of reference and electric potential limit  $\Phi_0$  ratio. In physics, there must be a theory of electric potential relativity (TEPR). It will be specifically used to describe the existence of the relationships between physical quantities such as space-time and the electric potential in the frames of reference with electric potential differences. STR is the study of physical parameters relationships such as space-time with speed in the inertial frames of references. Hence, there must be a higher theory of relativity that studies the relationship of the frames of reference with both speed difference and also an electric potential difference. This theory can be called the theory of electrodynamic space-time relativity, where STR and TEPR are both its special cases. In order to establish such "higher level theory of relativity," both the electric-charge state (equipotential) and the inertial motion state (inertial speed) of the same frame of reference must be unified. In modern physics, however, the concepts of electric potential and speed have no direct correlation. Through in-depth study, it was discovered that in order to solve this contradiction, new physical concepts such as imaginary motion, complex motion and etc., must be introduced.

Even though the equipotential frame of reference is very similar to the inertial frame of reference, but the equipotential frame of reference is stationary in the three-dimensional space. It cannot be defined as a regular inertial reference frame. Equipotential reference frame will be defined as the inertial frame of reference of the imaginary speed. There is a corresponding relationship that exists between electric potential and imaginary speed. The electric potential  $\Phi_0$  is equivalent to the imaginary speed of light  $C_0i$ . K is a conversion factor. That is:

$$V_{\phi}i = K\phi \tag{6}$$

$$C_0 i = K \Phi_0 \tag{7}$$

Where, unit imaginary number is  $i = \sqrt{-1}$ .

From equation (7)

$$K = \frac{C_0}{\Phi_0} i \tag{8}$$

K is an imaginary constant, and can be called the electrodynamic conversion factor.

To further investigate a universal space-time relationship, we must extend our concept of motion and space-time from the real number domain to the complex number domain. The more general motion can be abstractly understood as the motion state in the complex plane. If the motion in the coordinate reference system possesses both real and imaginary motion, then we call its motion state the complex motion state. The frame of reference situated in the complex motion state is called complex inertial electrodynamic frame of reference; it has both equipotential and inertial motion. The theory to describe this space-time relation of such motion is called the theory of complex electrodynamic space-time relativity.

As shown in Figure 1, let there be two complex coordinate systems of reference  $\Sigma_C(X, F, t)$  and  $\Sigma_C'(X', F', t')$  in the same complex plane. Their imaginary axis F and F', real axis X and X' are all parallel to each other. Since in complex number, there is no vector, therefore all the relevant physical parameters of motion must be scalars quantities such as speed and distance. Let  $\Sigma_C(X, F, t)$  be the stationary observing reference frame that is, the imaginary speed is zero (the electric potential is zero), and real speed is also zero. While  $\Sigma_C'(X', F', t')$  is the observed reference frame and in complex motion state relative to  $\Sigma_C(X, F, t)$ , its complex speed is  $V_w$ , its imaginary

speed is  $V_{\phi}i$ , and real speed is  $V_X$ , and  $\theta$  is the argument. When O' and O origin of coordinates overlap, let t = t' = 0.

$$V_{c} = V_{x} + V_{\phi}i = |V_{c}| e^{\theta i}$$

$$\tag{9}$$

The modulus of complex speed is: 
$$|V_c| = \sqrt{{V_x}^2 + {V_{\phi}}^2}$$
 (10)

Where, 
$$V_{\Phi} = \frac{\Phi C_0}{\Phi_0}$$
 (11)

Since real electric potential can be converted into imaginary speed, then by symmetry principle, real speed can be converted into imaginary electric potential  $\phi_x i$ . Therefore,  $\phi_x i = V_x \frac{1}{K} = -\frac{V_X \Phi_0}{C_0} i$ , where real electric potential  $\phi$  and imaginary electric potential  $\phi_x i$  together forms complex electric potential  $\phi_w$ :

$$\phi_{\rm c} = \phi + \phi_{\rm x} i \tag{12}$$

The modulus of complex electric potential is:

$$|\phi_{\rm c}| = \sqrt{\phi^2 + {\phi_{\rm x}}^2} \tag{13}$$

Where, 
$$\phi_{\rm x} = -\frac{V_{\rm x}\Phi_0}{C_0}$$
 (14)

Multiplying both sides of the equation (12) with the imaginary constant K, and comparing with the equation (9), we get:

$$V_{c} = K\phi_{c} \tag{15}$$

This shows that complex speed and the complex electric potential are inter-convertible. Therefore the complex reference frame of electric potential is a type of complex electrodynamic inertial reference frame. To take it one step further, the aforementioned four basic postulates will be combined into two basic postulates of TCESTR. Since complex numbers cannot be compared in magnitude, but their moduli can, we have:

- 5. The relative principle of complex electrodynamic space-time: the physical law has the same form in any complex electrodynamic inertial frame of reference;
- 6. The postulate of complex electrodynamic time-space limit: in any complex electrodynamic inertial reference system, the limit of complex speed's modulus of any point in the vacuum is a constant,  $C_0$ ; or the limit of complex electric potential's modulus of any point in the vacuum is a constant,  $\Phi_0$ .

Where,  $C_0$  is the speed of light in the vacuum with zero electric potential, and is equal to 299,792,458 m/sec. The limit of complex electric potential's modulus  $\Phi_0$  can only be determined by experiment.

One of the inference can be derived from postulate 6 is that in the frame of reference where the electric potential is not zero, the speed of light  $C_0$  in the real three-dimensional space is less than  $C_0$ . However, the complex speed's modulus of the light in the complex space is  $C_0$ . (This is proven in the subsequent paper regarding the expansion of Maxwell's equations).

When  $V_x = 0$ ,  $V_c = V_{\varphi}i$ , the two above postulates become the postulates of the theory of electric potential relativity. When  $V_{\varphi} = 0$ ,  $V_c = V_x$ , the two above postulates become the fundamental postulates of the special theory of relativity. Hence, special theory of relativity and the theory of electric potential relativity are two special cases of TCESTR.

The special theory of relativity is commonly referred to the motion of the observed system relative to the observing system along with an axis and is called the one-dimensional special theory of relativity. In fact, such motion can have two-dimensional or three-dimensional forms, and corresponding the special theory of relativity becomes more intricate but also more universal. There are already detailed discussions in literature on this matter, showing that in the real space two-dimensional <sup>[2]</sup> and three-dimensional special theory of relativity <sup>[3]</sup> in arbitrary direction can be derived through rotation and translation of the coordinate system of one-dimensional special theory

of relativity; or three-dimensional special theory of relativity [4], [5] can be derived through vector transformation of one-dimensional special theory of relativity. Although they are the difference in their derivation methods, there is a common theme, that is, through the use of the one-dimension special theory of relativity and appropriate mathematical approach, the higher dimension real form of the special theory of relativity can be derived. Therefore, based on the above-mentioned postulates and one-dimension special theory of relativity, TCESTR may be derived by way of transforming the complex coordinate system.

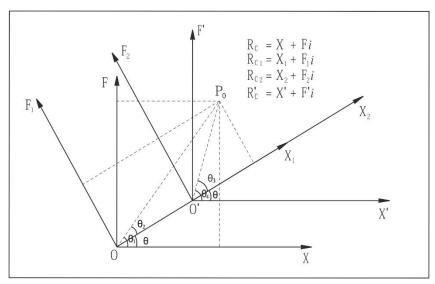


Figure 1

As shown in Figure 1, let there be a random point  $P_0$  be in the complex plane. In different complex coordinate systems, it can be represented by different coordinate parameters. In the complex coordinate system  $\Sigma_C(X, F, t)$ , the coordinate of  $P_0$  is represented by the complex distance  $R_c = X + Fi$  with argument is  $\theta_1$ . In the coordinate system  $\Sigma_C'(X', F', t')$ , the coordinate of point  $P_0$  is represented as complex distance  $R_c' = X' + F'i$  with argument  $\theta_4$ . Refer to method of two-dimensional coordinate transformation of real numbers  $P_0$  and expanding it into the complex planar space, reference system  $P_0(X', F', t')$  can be obtained through three times coordinate transformations from reference system  $P_0(X', F', t')$ .

- (1) In the complex coordinate system  $\Sigma_C(X, F, t)$ , its time is t, rotating the coordinate system by  $\theta$  degree counterclockwise, we get the complex coordinate system  $\Sigma_{C1}(X_1, F_1, t_1)$ , whose time is  $t_1$ ;
- (2) Complex coordinate system  $\Sigma_{C1}(X_1, F_1, t_1)$  is translated along axis  $X_1$  of a real number in quantity equal to the modulus of the complex speed  $|V_c|$ , we get the complex coordinate system  $\Sigma_{C2}(X_2, F_2, t_2)$ ., whose time is  $t_2$ ;
- (3) Complex coordinate system  $\Sigma_{C2}(X_2, F_2, t_2)$ . is rotated by  $\theta$  degree clockwise, we get the complex coordinate system  $\Sigma_{C}'(X', F', t')$ , whose time is t'.

The detailed derivation steps, numbered corresponding to the above, are as follow:

(1) Rotate the coordinate system  $\Sigma_C(X,F,t)$  by  $\theta$  degree counterclockwise, making the real axis  $X_1$  of the coordinate system  $\Sigma_{C1}(X_1,F_1,t_1)$  pass through the origin O' of the reference system  $\Sigma_C'(X',F',t')$ . Point  $P_0$  in  $\Sigma_C(X,F,t)$  the complex coordinate system has complex distance  $R_c$ , whose argument is  $\theta_1$ . Point  $P_0$  in the coordinate system  $\Sigma_{C1}(X_1,F_1,t_1)$  has complex distance  $R_{c1}$ , whose argument is  $\theta_2$ . That is,

$$R_c = X + Fi = |R_c|e^{\theta_1 i} \tag{16}$$

$$R_{c1} = X_1 + F_1 i = |R_{c1}| e^{\theta_2 i}$$
(17)

Also,  $|R_c| = |R_{c1}|$ , therefore,

$$R_{c1} = R_c e^{(\theta_2 - \theta_1)i}$$
(18)

$$R_{c1} = R_c e^{-\theta i} \tag{19}$$

$$R_{c1} = (X + Fi)(\cos\theta - i\sin\theta) \tag{20}$$

From equations (20) and (17),

$$X_1 = X\cos\theta + F\sin\theta \tag{21}$$

$$F_1 = F\cos\theta - X\sin\theta \tag{22}$$

(2) Let  $\Sigma_{C1}(X_1, F_1, t_1)$  be the stationary frame of reference whose time is  $t_1$ .  $\Sigma_{C2}(X_2, F_2, t_2)$  is the moving reference system whose time is  $t_2$ , and real axes  $X_1$  and  $X_2$  are overlapping. The reference system  $\Sigma_{C2}(X_2, F_2, t_2)$  moves along the positive  $X_1$  direction relative to  $\Sigma_{C1}(X_1, F_1, t_1)$  with the magnitude of  $|V_c|$ , hence  $F_2 = F_1$ . Since  $X_1$  is the real number axis of  $\Sigma_{C1}(X_1, F_1, t_1)$ , it can be thought of the real motion. This is the same state that the special theory of relativity studies. Hence the Lorentz transform equations (1), (2), (4) and (5) can be directly used, but the parameters in the equations need to be replaced by the parameters of  $\Sigma_{C1}(X_1, F_1, t_1)$  and  $\Sigma_{C2}(X_2, F_2, t_2)$ .

According to the postulate of complex electrodynamic time-space limit, the moduli of the complex speed of light in all directions are a constant  $C_0$ . When a coordinate system rotates around itself origin to an angle, the two origins of coordinate systems before and after the rotation have not been displaced. Their complex distances' moduli are equal between the origins and point  $P_0$ . When the light beamed from origins to  $P_0$  point, the times spent are the same. Therefore time is not related to the angle of coordinate system rotation, that is  $t = t_1$ ,  $t_2 = t'$ . We get,

$$X_2 = \gamma(X_1 - |V_c|t) \tag{23}$$

$$F_2 = F_1 \tag{24}$$

$$t' = \gamma \left( t - \frac{|V_c|}{G_0^2} X_1 \right) \tag{25}$$

Where, 
$$\gamma = \frac{1}{\sqrt{1 - \frac{|V_c|^2}{C_0^2}}}$$
 (26)

(3) In the complex coordinate reference system  $\Sigma_{C2}(X_2, F_2, t_2)$ .,  $P_0$  is represented by the complex distance  $R_{w_2}$  with an argument  $\theta_3$ , rotating clockwise  $\theta$  degree, we get the coordinate system  $\Sigma_{C}'(X', F', t')$ . In  $\Sigma_{C}'(X', F', t')$ ,  $P_0$  is represented by the complex distance  $R_{C}'$  with a argument  $\theta_4$ :

$$R_{c2} = X_2 + F_2 i = |R_{c2}| e^{\theta_3 i}$$
(27)

$$R_{c}' = X' + F'i = |R_{c}'|e^{\theta_{4}i}$$
(28)

And also,  $|R_c'| = |R_{c2}|$ , hence,

$$R_{c}' = R_{c2} e^{(\theta_4 - \theta_3)i} = R_{c2} e^{\theta i}$$
(29)

Because  $R_{c2} - R_{c1} = X_2 - X_1$ , therefore,

$$R_{c}' = (R_{c1} - (X_1 - X_2)) e^{\theta i}$$
(30)

Substituting equation (19) into equation(30),

$$R_{c}' = R_{c} - (X_{1} - X_{2}) e^{\theta i}$$
(31)

Because  $V_c = |V_c|e^{\theta i}$ , therefore,

$$R_{c}' = R_{c} - V_{c} \frac{(X_{1} - X_{2})}{|V_{c}|}$$
(32)

Let 
$$t_c = \frac{(X_1 - X_2)}{|V_c|}$$
 (33)

 $t_c$  is a real number, and can be called the system time of complex electrodynamic inertial reference frames. It is not a special time for any particular reference frame but related to the time of both the observing system and the

observed system. The following discusses the relationship between the system time  $t_c$ , the observed time t of the frame of reference, and the time t' of the observed frame of reference:

From equation (25),

$$X_1 = \frac{C_0^2}{|V_c|} t - \frac{1}{v} \frac{C_0^2}{|V_c|} t' \tag{34}$$

Substituting equation (34) into equation (23),

$$X_2 = \frac{1}{\gamma} \frac{{C_0}^2}{|V_c|} t - \frac{{C_0}^2}{|V_c|} t'$$
(35)

Substituting equations (34) and (35) into the equation (33),

$$t_{c} = \left(1 - \frac{1}{\gamma}\right) \frac{C_{0}^{2}}{|V_{c}|^{2}} (t + t') \tag{36}$$

It can be seen that the system time  $t_c$  unites the stationary reference frame time t and the motion reference frame time t', and that t and t' are exactly equal position in system time.

Due to the relativity of the motions, the magnitude of the relative velocity of motion between the reference frames, regardless of whether it is measured by the observer in the reference frame  $\Sigma_c(X,F,t)$  or  $\Sigma_c'(X',F',t')$ , is equal to  $|V_c|$ , and the sum of the time of the two frames of reference measured by this observer (t+t') is also equal. Let the system time measured in  $\Sigma_c(X,F,t)$  is  $t_c$ , and the system time measured in  $\Sigma_c'(X',F',t')$  is  $t_c'$ , so there is  $t_c=t_c'$ . That is, system time has nothing to do with the choice of the reference system. It is a new way to express time.

Finally, we obtain the basic equations for TCESTR expressed in system time  $t_c'$  and  $t_c'$  as the following:

$$R_c' = R_c - V_c t_c \tag{37}$$

$$t_{c}' = t_{c} \tag{38}$$

The form of the basic equations is as concise as that of the Galilean transformation. But their physical content is richer, and special relativity is only one of its special cases. The basic equations contain the following equation:

$$\gamma = \frac{1}{\sqrt{1 - \frac{|V_{\rm c}|^2}{{C_0}^2}}} \tag{39}$$

$$t' = \gamma \left( t - \frac{|V_c|}{{C_0}^2} X_1 \right) \tag{40}$$

$$X_2 = \gamma(X_1 - |V_c|t) \tag{41}$$

$$X_1 = X\cos\theta + F\sin\theta \tag{42}$$

$$t_{c} = \frac{(X_{1} - X_{2})}{|V_{c}|} \tag{43}$$

$$t_{c} = \left(1 - \frac{1}{\gamma}\right) \frac{C_{0}^{2}}{|V_{c}|^{2}} (t + t') \tag{44}$$

Depending on different applications, the above relationship can be further expanded into different forms.

Because of Euler formula, 
$$e^{\theta i} = \cos \theta + i \sin \theta$$
 (45)

According to equations (9) and (45), There are  $\cos\theta = \frac{V_x}{|V_c|}$  and  $\sin\theta = \frac{V_{\phi}}{|V_c|}$ . Substituting them into equation (42), we get:

$$X_{1} = \frac{1}{|V_{c}|} (XV_{x} + FV_{\phi}) \tag{46}$$

According to equations (43)(41)(46) and (37), we can obtain equation (47). Therefore, to further summarize, another expression of the basic equations of TCESTR can be obtained. That is, the extended basic equations expressed by complex speed and reference system time t and t' is as follow:

$$R_{c}' = R_{c} - \frac{V_{c}}{|V_{c}|} ((1 - \gamma)X_{1} + |V_{c}|\gamma t)$$
(47)

$$t' = \gamma \left( t - \frac{|V_c|}{{c_0}^2} X_1 \right) \tag{48}$$

Where, 
$$\gamma = \frac{1}{\sqrt{1 - \frac{|V_c|^2}{c_0^2}}}$$

Speed and electric potential have a corresponding relationship. Therefore, we can also obtain another set extended basic equations for describing TCESTR with complex electric potential, and reference system time t, and t'. This will be discussed later in the quaternion electrodynamic space-time relativity.

By decomposing (47) into equations of a real number and an imaginary number, we obtain:

$$X' = X - \frac{V_x}{|V_c|} \left( (1 - \gamma) X_1 + |V_c| \gamma t \right) \tag{49}$$

$$F'i = Fi - i \frac{V_{\phi}}{|V_c|} \left( (1 - \gamma)X_1 + |V_c|\gamma t \right)$$

$$(50)$$

Therefore when  $V_{\varphi} = 0$  and  $V_{x} > 0$ , then  $|V_{c}| = V_{x}$ , according to (46) can get  $X_{1} = X$ , and, Substituting the equations into (49), (50), (40) and (39), the special theory of relativity can be obtained:

$$X' = \gamma(X - V_X t) \tag{51}$$

$$t' = \gamma \left( t - \frac{V_{x}}{C_{0}^{2}} X \right) \tag{52}$$

$$F' = F \tag{53}$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{V_X^2}{c_0^2}}} \tag{54}$$

Let  $V_x = 0$  and  $V_{\varphi} > 0$ , then  $|V_c| = V_{\varphi}$ ,  $|V_c| = \frac{c_0}{\Phi_0} \varphi$  can be obtained based on equation (6) and (7), and according to (46) can obtain  $X_1 = F$ . Substituting the equations into (49), (50), (40) and (39), a new special theory of relativity can be obtained:

$$F'i = \gamma \left( Fi - \frac{C_0}{\Phi_0} \phi it \right) \tag{55}$$

$$X' = X \tag{56}$$

$$t' = \gamma \left( t - \frac{\phi}{\Phi_0 C_0} F \right) \tag{57}$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{\phi^2}{{\Phi_0}^2}}}\tag{58}$$

This is the aforementioned the theory of electric potential relativity (TEPR), whose form can be seen here as symmetric to that of the special theory of relativity, but they have different physical meaning.

#### Part 2. The theory of quaternion electrodynamic space-time relativity

TCESTR describes the relationship between the space-time and the state of complex motion of the reference frames in the complex plane, but the real axis in the complex plane is one-dimensional. In reality, our real number space is three-dimensional. Therefore, two-dimensional space of TCESTR must be expanded into four dimensions. In mathematics, quaternion us the higher form of the complex number. Let A be a quaternion,

$$\mathbf{A} = \mathbf{z}_1 + \mathbf{z}_2 \mathbf{i} + \mathbf{z}_3 \mathbf{j} + \mathbf{z}_4 \mathbf{k} \tag{59}$$

Where, i, j, k are the unit vectors, and they satisfy the multiplication rules of quaternion. If  $z_n$  (n = 1, 2, 3, 4,) are all real number, then A is a real quaternion. If there is at least one complex number (or one imaginary number)

in  $z_n$ , then A is called biquaternion<sup>[6]</sup>. The real quaternion is a special case of biquaternion. The modulus |A| of the quaternion A is

$$|A|^2 = z_1^2 + z_2^2 + z_3^2 + z_4^2 \tag{60}$$

If A is biquaternion, then under normal condition |A| is a complex number. However, because complex numbers cannot be compared in magnitude, The paper need to define another modulus ||A|| of the quaternion A, where

$$||A||^2 = |z_1|^2 + |z_2|^2 + |z_3|^2 + |z_4|^2$$
(61)

Here  $|z_n|$  (n = 1,2,3,4) is the absolute value of  $z_n$ , ||A|| is a norm. Therefore, ||A|| can be called the norm-modulus of quaternion A, and it is a real number that is greater or equal to zero. When A is real quaternion, we get,

$$||A|| = |A| \tag{62}$$

Hence, in order to further expand TCESTR into TQESTR, the physical parameters within the TCESTR must be expanded to become quaternion physical parameters. For example, quaternion velocity, quaternion electric potential and etc., whose corresponding reference system would be collectively referred to as the quaternion electrodynamic inertial reference system. At the same time, the two basic postulates 5 and 6 of TCESTR can be further expanded into the basic postulates of TQESTR:

- 7. The relative principle of quaternion electrodynamic space-time: in any quaternion electrodynamic inertial reference system, physical laws have the same form;
- 8. The postulate of quaternion electrodynamic space-time limit: in any quaternion electrodynamic inertial reference system, the limit of quaternion velocity's norm-modulus of any point in the vacuum is a constant,  $C_0$ ; or the limit of quaternion electric potential's norm-modulus of any point is a constant,  $\Phi_0$ .

Where  $C_0$  is the speed of light in the vacuum with zero electric potential, and is equal to 299,792,458 m/sec. The limit of quaternion electric potential's modulus  $\Phi_0$  only can be determined by experiment.

According to the basic equation (37) of TCESTR, it can be expanded and separated into real number equation and imaginary number equation:

$$F'i = Fi - V_{\phi}it_{c} \tag{63}$$

$$X' = X - V_X t_C \tag{64}$$

Notice that equation (64) is a real scalar expression. However, the fact is that the observed reference frame  $\Sigma_C'(X', F', t')$  moves along the real axis X of the observing reference frame  $\Sigma_C(X, F, t)$  with vector velocity  $\mathbf{V_x}$ . Let its unit vector be  $\mathbf{i}$ , because axes X' and X are the same direction as  $\mathbf{i}$ . Multiply both sides of equation (64) by  $\mathbf{i}$ , equation (64) becomes a vector equation:

$$\mathbf{X}' = \mathbf{X} - \mathbf{V_x} \mathbf{t_c} \tag{65}$$

Equations (63) and (65) describe the physical nature more objectively than the complex equations(37). So the physical quantities of motion will also use a vector, such as velocity, displacement and etc. The equation can be expanded into three-dimensional. If the vector  $\mathbf{X}'$  and  $\mathbf{X}$  in equation (65) are defined as vector  $\mathbf{r}'$  and  $\mathbf{r}$  in the three-dimensional space  $\mathbf{X}'$ ,  $\mathbf{Y}'$ ,  $\mathbf{Z}'$  and  $\mathbf{X}$ ,  $\mathbf{Y}$ ,  $\mathbf{Z}$ , corresponding velocity  $\mathbf{V}_{\mathbf{x}}$  is defined as  $\mathbf{V}_{\mathbf{r}}$ , and have the same direction as  $\mathbf{r}'$ ,  $\mathbf{r}$  and  $\mathbf{V}_{\mathbf{r}}$ . Let  $\mathbf{i}$ ,  $\mathbf{j}$ ,  $\mathbf{k}$  be the unit vectors in the coordinate of three-dimensional space along the axis  $\mathbf{X}$ ,  $\mathbf{Y}$ ,  $\mathbf{Z}$ , respectively, we have:

$$\mathbf{r} = \mathbf{X}\mathbf{i} + \mathbf{Y}\mathbf{j} + \mathbf{Z}\mathbf{k} \tag{66}$$

$$\mathbf{r}' = \mathbf{X}'\mathbf{i} + \mathbf{Y}'\mathbf{j} + \mathbf{Z}'\mathbf{k} \tag{67}$$

$$\mathbf{V_r} = \mathbf{V_x} \mathbf{i} + \mathbf{V_y} \mathbf{j} + \mathbf{V_z} \mathbf{k} \tag{68}$$

X', X,  $V_x$  becomes r', r,  $V_r$ . At the same time, let  $t_c$  become  $t_q$  accordingly. Therefore, equation (63) and (65) can be transformed into:

$$F'i = Fi - V_{\phi}it_{\alpha} \tag{69}$$

$$\mathbf{r}' = \mathbf{r} - \mathbf{V}_{\mathbf{r}} \mathbf{t}_{\mathbf{0}} \tag{70}$$

Equation (69) and (70) form a quaternion space system composed of three real number vectors and one imaginary number, and is called type  $A_i$  quaternion space. This expands the state of motion of the reference system in the complex plane into motion of the type  $A_i$  quaternion space, that is, the reference system  $\Sigma_Q'(F',X',Y',Z',t')$  moves with quaternion velocity  $V_q$  relative to the reference frame  $\Sigma_Q(F,X,Y,Z,t)$ . Suppose quaternion distance  $R'_q$  and  $R_q$  are quaternion displacement coordinates at any point  $P_0$  in the inertial reference system  $\Sigma_Q'(F',X',Y',Z',t')$  and  $\Sigma_Q(F,X,Y,Z,t)$  in the  $A_i$  type quaternion space, respectively, then:

$$R_{q} = Fi + \mathbf{r} = Fi + X\mathbf{i} + Y\mathbf{j} + Z\mathbf{k}$$

$$\tag{71}$$

The norm-modulus of 
$$R_q$$
 is  $||R_q||$  that is  $||R_q|| = \sqrt{F^2 + X^2 + Y^2 + Z^2}$  (72)

$$R'_{q} = F'i + \mathbf{r}' = F'i + X'i + Y'j + Z'k$$
(73)

The norm-modulus of 
$$R'_q$$
 is  $||R'_q||$ , i.e.,  $||R'_q|| = \sqrt{F'^2 + X'^2 + Y'^2 + Z'^2}$  (74)

Type  $A_i$  quaternion velocity  $V_q$  and its norm-modulus  $||V_q||$  are:

$$V_{q} = V_{\phi}i + V_{r} = V_{\phi}i + V_{X}i + V_{Y}j + V_{Z}k$$

$$(75)$$

$$||V_{q}|| = \sqrt{V_{r}^{2} + V_{\phi}^{2}} = \sqrt{V_{X}^{2} + V_{Y}^{2} + V_{Z}^{2} + V_{\phi}^{2}}$$
(76)

Where  $i = \sqrt{-1}$ 

Adding equation (69) with (70), and substituting (71), (73) and (75) into it to obtain equation (77). Also, replacing  $X', X_1, X_2, X, t_c, t'_c$  and  $|V_c|$  of equations (37)(38)(39)(40)(41)(42)(43)and(44) with  $r', r_1, r_2, r, t_q, t'_q$  and  $||V_q||$ , The fundamental equations can be obtained for TQESTR:

$$R_q' = R_q - V_q t_q \tag{77}$$

$$t_{\mathbf{q}}' = t_{\mathbf{q}} \tag{78}$$

The mathematical form of the fundamental equation above is still the same as that of the Galilean transformation. But its physical meaning is universal, and they have reached a higher level than that of complex relativity both in mathematical structure and in physical meaning. The fundamental equations contain the following equations:

where,
$$\gamma = \frac{1}{\sqrt{1 - \frac{||V_q||^2}{c_0^2}}}$$
 (79)

$$t' = \gamma \left( t - \frac{||V_q||}{{C_0}^2} r_1 \right) \tag{80}$$

$$r_1 = r\cos\theta + F\sin\theta \tag{81}$$

$$\mathbf{r}_2 = \gamma (\mathbf{r}_1 - ||\mathbf{V}_0||\mathbf{t}) \tag{82}$$

$$t_{q} = \frac{(r_{1} - r_{2})}{||V_{q}||} \tag{83}$$

$$t_{q} = (1 - \frac{1}{v}) \frac{C_{0}^{2}}{||V_{0}||^{2}} (t + t')$$
(84)

Depending on the need, the above basic equations can be transformed into different variations.

Because of 
$$\cos\theta = \frac{V_r}{||V_q||}$$
,  $\sin\theta = \frac{V_{\varphi}}{||V_q||}$ ,  $r = X\frac{V_X}{V_r} + Y\frac{V_Y}{V_r} + Z\frac{V_Z}{V_r}$ , then,

$$r_1 = \frac{1}{||V_0||} (FV_{\phi} + XV_X + YV_Y + ZV_Z)$$
 (85)

According to equations (85)(82)(83) and (77), we can obtain equation (86). The extended basic equations of TQESTR can be expressed using the quaternion velocity, t and t' as the following:

$$R_{q}' = R_{q} - \frac{V_{q}}{||V_{q}||} ((1 - \gamma)r_{1} + ||V_{q}||\gamma t)$$
(86)

$$t' = \gamma \left( t - \frac{||V_q||}{C_0^2} r_1 \right) \tag{87}$$

Where, 
$$\gamma = \frac{1}{\sqrt{1 - \frac{||V_q||^2}{c_0^2}}}$$
 (88)

When  $V_{\varphi} = 0$ , Based on equations(62), (71), (73) and (75)  $||V_q|| = |V_r|$ ,  $R_q = r$ ,  $R_q' = r'$ ,  $V_q = V_r$  can be obtained. According to equation (85), and then,

$$\mathbf{r}_1 = \frac{\mathbf{r} \cdot \mathbf{V}_{\mathbf{r}}}{|\mathbf{V}_{\mathbf{r}}|} \tag{89}$$

Therefore the special theory of relativity in any direction  $\mathbf{r}(\mathbf{x}, \mathbf{y}, \mathbf{z})$  in three-dimensional space can be obtained [4] [5].

$$\mathbf{r}' = \mathbf{r} - \frac{\mathbf{v}_{r}}{|\mathbf{v}_{r}|} ((1 - \gamma) \frac{\mathbf{r} \cdot \mathbf{v}_{r}}{|\mathbf{v}_{r}|} + |\mathbf{v}_{r}| \gamma t)$$

$$\tag{90}$$

$$t' = \gamma \left( t - \frac{r \cdot V_r}{{c_0}^2} \right) \tag{91}$$

Where, 
$$\gamma = \frac{1}{\sqrt{1 - \frac{|V_{\Gamma}|^2}{C_0^2}}}$$
 (92)

Because of imaginary speed  $V_{\varphi}$  and real electric potential  $\varphi$  are inter-convertible, and real velocity can be converted into an imaginary electric potential vector. Hence the quaternion velocity equations can be converted into another type of quaternion electric potential equations. The quaternion is composed of one real and three imaginary vectors. It is called  $B_i$  type quaternion. Through further analysis,  $B_i$  type quaternion is also a type of biquaternion [6].

Let  $B_i$  type quaternion electric potential be  $\phi_h$ , then:

$$\phi_{\mathbf{q}} = \frac{V_{\mathbf{q}}}{K} = (V_{\mathbf{p}}i + V_{\mathbf{X}}\mathbf{i} + V_{\mathbf{Y}}\mathbf{j} + V_{\mathbf{Z}}\mathbf{k})\frac{\Phi_{0}}{C_{0}}(-i)$$
(93)

Let  $\varphi=\frac{V_{\varphi}\Phi_0}{C_0}$  ,  $\varphi_X=\frac{V_X\Phi_0}{C_0}$  ,  $\varphi_Y=\frac{V_Y\Phi_0}{C_0}$  ,  $\varphi_Z=\frac{V_Z\Phi_0}{C_0}$  , then:

$$\phi_{h} = \phi + (\phi_{X}\mathbf{i} + \phi_{Y}\mathbf{j} + \phi_{Z}\mathbf{k})(-i)$$
(94)

This shows that  $B_i$  type quaternion potential  $\phi_h$  is composed of one scalar electric potential and three imaginary components of the vector electric potential.

According to the equation (93) from the definition of  $\phi_h$ , we get:

$$\frac{\mathbf{v_q}}{||\mathbf{v_q}||} = i \frac{\mathbf{\phi_q}}{||\mathbf{\phi_q}||} \tag{95}$$

Because 
$$||V_{\mathbf{q}}|| = \frac{C_0}{\Phi_0} ||\Phi_{\mathbf{q}}||$$
 (96)

Substituting equations (95),(96) into equations (86), (87) and (88), the extended basic equations describing TQESTR with the quaternion electric potential, t and t' are as the following:

$$R_{q}' = R_{q} - i \frac{\phi_{q}}{||\phi_{q}||} \left( (1 - \gamma) r_{1} + \frac{C_{0}}{\phi_{0}} ||\phi_{q}|| \gamma t \right)$$
(97)

$$t' = \gamma \left( t - \frac{||\phi_q||}{|\phi_0 C_0|} r_1 \right) \tag{98}$$

Where, 
$$\gamma = \frac{1}{\sqrt{1 - \frac{||\phi q||^2}{{\Phi_0}^2}}}$$
, (99)

The above equation can be further simplified into the theory of complex electric potential relativity, the theory of electric potential relativity (TEPR) and other forms.

Although the content of the theory of electrodynamic space-time relativity is abundant, its fundamental postulates and the fundamental postulates of the special theory of relativity are the same in the core idea. they are still the principle of invariance of light speed and the principle of relativity. Therefore, the concept of "spacetime interval " in the special theory of relativity can be naturally extended to the theory of quaternion electrodynamic space-time relativity. At the same time, the mathematical expression of the invariance of light speed in the theory of quaternion electrodynamic space-time relativity can be obtained

$$X'^{2} + Y'^{2} + Z'^{2} + F'^{2} - C_{0}^{2}t'^{2} = X^{2} + Y^{2} + Z^{2} + F^{2} - C_{0}^{2}t^{2}$$
(100)

Through mathematical transformation, the basic equations (86) and (87) of the theory of quaternion electrodynamic space-time relativity are substituted into the above equation to validate. The equation is proven to be valid (detailed proof of the process to see Appendix A). In other words, the theory of quaternion electrodynamic space-time relativity is theoretically self-consistent. Of course, it must also undergo rigorous experimental testing. Hence, the topics discussed below will provide the basis for future experiments.

#### Part 3. Discussion on the basic effects of TQESTR

Although TQESTR has various expression forms, the forms can all be obtained through conversion and simplification of basic the equations (77), (80), (79), (81), (82) and (83). Therefore, they will be the main focus for the discussions of the basic effects of TQESTR. The effects are called electrodynamic space-time effect.

# 1. Superposition principle of TQESTR

By analyzing the above equations, one can see that the equations (82) and (80) have the same form as that of Lorentz transform equations (1) and (4). Therefore, the equations (82), (80) and (79) can also be written in the form of hyperbolic functions [5],

$$r_2 = r_1 \cosh(\varphi) - C_0 \tanh(\varphi) \tag{101}$$

$$C_0 t' = -r_1 \sinh(\varphi) + C_0 t \cosh(\varphi) \tag{102}$$

$$C_0 t' = -r_1 \sinh(\varphi) + C_0 \cosh(\varphi)$$

$$\text{Where, } \cosh(\varphi) = \frac{1}{\sqrt{1 - (\frac{||V_q||}{C_0})^2}}$$

$$(103)$$

Because 
$$\cosh^2(\varphi) - \mathrm{sigh}^2(\varphi) = 1$$
 (104)

From(103) and(104) it can be obtained: 
$$tanh(\varphi) = \frac{||V_q||}{C_0}$$
 (105)

Assume:  $\varphi = \varphi_1 + \varphi_2$ ,  $\frac{||V_{q1}||}{C_0} = \tanh(\varphi_1)$  and  $\frac{||V_{q2}||}{C_0} = \tanh(\varphi_2)$ 

$$\frac{||V_q||}{c_0} = \tanh(\varphi_1 + \varphi_2) \tag{106}$$

According to the equation (106), the formula for superposition of velocity of TQESTR can be obtained:

$$||V_{\mathbf{q}}|| = \frac{||V_{\mathbf{q}2}|| + ||V_{\mathbf{q}1}||}{1 + \frac{||V_{\mathbf{q}1}|| \cdot ||V_{\mathbf{q}2}||}{C_{\mathbf{q}^2}}}$$
(107)

Where, 
$$||V_{q1}|| = \sqrt{V_{\phi 1}^2 + V_{X1}^2 + V_{Y1}^2 + V_{Z1}^2}$$
 (108)

$$||V_{q2}|| = \sqrt{V_{\phi 2}^2 + V_{X2}^2 + V_{Y2}^2 + V_{Z2}^2}$$
(109)

When the direction of motion of the reference frame is along X-axis, and,  $V_{x1}$ ,  $V_{x2}$  are positive real numbers.  $||V_q|| = V_x$ ,  $||V_{q1}|| = V_{x1}$ ,  $||V_{q2}|| = V_{x2}$ , All other terms are zero. By substituting the above-mentioned formula of superposition, the formula for velocity superposition of special theory of relativity can be obtained:

$$V_{X} = \frac{V_{X2} + V_{X1}}{1 + \frac{V_{X1}V_{X2}}{C_{0}^{2}}} \tag{110}$$

According to the equation (96), the quaternion velocity equations can be converted into quaternion electric potential equations. Substitute equation (96) into (107), The formula for superposition of quaternion electric potential of TQESTR can be obtained:

$$||\phi_{\mathbf{q}}|| = \frac{||\phi_{\mathbf{q}2}|| + ||\phi_{\mathbf{q}1}||}{1 + \frac{||\phi_{\mathbf{q}1}|| ||\phi_{\mathbf{q}2}||}{|\phi_{\mathbf{p}}|^2}}$$
(111)

When the only the scalar electric potential is considered, and,  $\phi_1$ ,  $\phi_1$  are positive real numbers.  $||\phi_q|| = \phi$ ,  $||\phi_{q1}|| = \phi_1$ ,  $||\phi_{q2}|| = \phi_1$ , other terms are all zero. By substituting the above-mentioned formula, the formula for superposition of scalar electric potential can be obtained:

$$\phi = \frac{\phi_2 + \phi_1}{1 + \frac{\phi_1 \phi_2}{\phi_0^2}} \tag{112}$$

Thus a conclusion that differs from the modern physics is deduced: the superposition of electric potential is nonlinear. However, if the electric potential is far lower than the electric potential limit, the equation (112) will change back to a linear equation of the current electromagnetics, that is  $\phi = \phi_2 + \phi_1$ .

#### 2. The time relationship of TQESTR

In any electrodynamic inertia frame of reference, time is isotropic. The time measured by the clock put in the real space of the inertial frame is the time of the electrodynamic inertial frame. If two events happen at two different moments  $t_1$  and  $t_2$  at the same location  $r_1$  of the electrodynamic stationary inertial reference frame, their time difference is  $\Delta t = t_2 - t_1$ ; for the moments  $t_1'$  and  $t_2'$  corresponding to the electrodynamic relative inertial reference frame, the time difference is  $\Delta t' = t_2' - t_1'$ . From equations(80), (79) and (76), the equation of velocity-time effect of TQESTR is:

$$\Delta t' = \frac{1}{\sqrt{1 - \frac{V_{\phi}^2 + V_{\chi}^2 + V_{\gamma}^2 + V_{z}^2}{c_0^2}}} \Delta t \tag{113}$$

It shows that the expansion effect of the time is not just about speed, but with electric potential.

The expression for the electric potential-time effect of TQESTR is:

$$\Delta t' = \frac{1}{\sqrt{1 - \frac{\phi^2 + \phi_X^2 + \phi_Y^2 + \phi_Z^2}{\phi_0^2}}} \Delta t \tag{114}$$

In the reference frame of complex electrodynamic inertia, i.e., there are only electric potential  $\varphi$  and one dimensional speed  $V_X$ , from  $V_{\varphi} = \frac{c_0}{\Phi_0} \varphi$ , it can be obtained:

$$\Delta t' = \frac{1}{\sqrt{1 - \frac{v_X^2}{c_0^2} - \frac{\phi^2}{\Phi_0^2}}} \Delta t \tag{115}$$

In(115), when  $\phi = 0$ , the formula for time expansion of special relativity is obtained:

$$\Delta t' = \frac{1}{\sqrt{1 - \frac{v_X^2}{c_0^2}}} \Delta t \tag{116}$$

In(115),  $V_X = 0$ , the formula for the time expansion effect of electric potential relativity theory is obtained:

$$\Delta t' = \frac{1}{\sqrt{1 - \frac{\phi^2}{\Phi_0^2}}} \Delta t \tag{117}$$

This is a new important physical effect, called it the electric potential time expansion effect.

# 3. Space change effect of TQESTR

In the stationary electrodynamic reference frame  $\Sigma_Q$ , event A  $(F_1, X_1, Y_1, Z_1, t_1)$  and event B  $(F_2, X_2, Y_2, Z_2, t_2)$  occur, the corresponding events in the moving electrodynamic frames of reference  $\Sigma_Q$ ' are event A'  $(F_1', X_1', Y_1', Z_1', t_1')$  and event B'  $(F_2', X_2', Y_2', Z_2', t_2')$ ,  $V_q$  is the relative quaternion velocity of two reference frames. Therefore from the equation(77), the expressions of the space coordinates of the two events are:

$$R_{q1}' = R_{q1} - V_{q}t_{q1} \tag{118}$$

$$R_{q2}' = R_{q2} - V_q t_{q2} \tag{119}$$

So there is, 
$$\Delta R_q' = \Delta R_q - V_q \Delta t_q$$
 (120)

Where,  $\Delta R_q = R_{q2} - R_{q1}$  ,  $\Delta R_q{'} = R_{q2}{'} - R_{q1}{'}$ 

From equation (84),

$$\Delta t_{q} = \left(1 - \frac{1}{\gamma}\right) \frac{C_0^2}{||V_{q}||^2} \left(\Delta t + \Delta t'\right) \tag{121}$$

Where,  $\Delta t_q = t_{q2} - t_{q1}$ ,  $\Delta t = t_2 - t_1$ ,  $\Delta t' = t_2' - t_1'$ 

From equation (80), 
$$\Delta t' = \gamma \left( \Delta t - \frac{||V_q||}{{C_0}^2} \Delta r_1 \right)$$
 (122)

In the stationary electrodynamic frame of reference, the time can be different when reading the space parameters of the event A and event B. However, in the moving electrodynamic frames of reference, the reading of event A' and event B' must be completed at the same time. Therefore,  $\Delta t' = 0$ . Substituting  $\Delta t' = 0$  into equations (121) and (122) obtains:

$$\Delta t_{q} = \frac{\left(1 - \frac{1}{\gamma}\right) \Delta r_{1}}{||V_{q}||} \tag{123}$$

By substituting(123) into(120), the equation of space-velocity effect of TQESTR can be obtained:

$$\Delta R_{\mathbf{q}}' = \Delta R_{\mathbf{q}} - \frac{V_{\mathbf{q}}}{\|V_{\mathbf{q}}\|} \left(1 - \frac{1}{\gamma}\right) \Delta r_{1} \tag{124}$$

Where 
$$\Delta r_1 = \Delta r \cos\theta + \Delta F \sin\theta$$
 (125)

The equation (124) is expanded into the equations of imaginary and vector equations of real number:

$$\Delta F' i = \Delta F i - i \frac{V_{\phi}}{||V_{\alpha}||} \left(1 - \frac{1}{\gamma}\right) \Delta r_1 \tag{126}$$

$$\Delta \mathbf{r}' = \Delta \mathbf{r} - \frac{\mathbf{v_r}}{||\mathbf{v_q}||} \left(1 - \frac{1}{\gamma}\right) \Delta \mathbf{r}_1 \tag{127}$$

When  $V_{\Phi} \neq 0$ ,  $V_{r} = 0$ ,  $\theta = \frac{\pi}{2}$ ,  $\Delta r_{1} = \Delta F$ , there is:

$$\Delta \mathbf{r}' = \Delta \mathbf{r} \tag{128}$$

The scalar form of the above equation:  $\Delta r' = \Delta r$ , That is, in any equipotential space of relative stationary, the real space length is not related to the scalar electric potential. It can be called the effect of electric potential space unchanged.

When 
$$V_{\phi} = 0$$
,  $V_{\mathbf{r}} \neq 0$ ,  $||V_{\mathbf{q}}|| = V_{\mathbf{r}}$ ,  $\theta = 0$ ,  $\Delta \mathbf{r}_1 = \Delta \mathbf{r}$ 

$$\Delta \mathbf{r}' = \frac{1}{\gamma} \Delta \mathbf{r}$$
(129)

The scalar form of the above equation:  $\Delta r' = \frac{1}{\gamma} \Delta r$ , This is the formula for length contraction of the special theory of relativity.

Substituting equations (95) and (96) into (124), the equation of electric potential-space effect can be obtained. At the same time, it can also be simplified under certain conditions.

### 4. Predictions and verifications of the theory

The above derivations indicate that in the theory of electrodynamic space-time relativity, time and space not only are related to the three-dimensional velocity but also related to electric potential. In principle, different experiments can be designed to verify the theory. Amongst them, the effect of electric potential time expansion can be more easily tested.

The equation shows that under completely stationary conditions when there is the sufficiently high electric potential difference between two reference frames, their time difference will also be found. If the electric potential is higher, this effect will be more obvious. Therefore, an experiment may be designed: after calibration, two clocks of high precision  $T_c$  and  $T_d$  are put separately in two identical metallic closed rooms C and D, which are isolated and motionless relative to each other. Room C is grounded and let its electric potential be zero. An electric potential generator of super high voltage is used to charge room D and maintain the super high electric potential  $\varphi$  comparing to room C. Equation (117) indicates that given long enough time after electricity of room D is totally discharged, the electric potential in room D becomes zero again. Then two clocks  $T_c$  and  $T_d$  are put together to compare their respective reading of the elapsed time,  $\Delta t$ , and  $\Delta t'$ . It can be found that there is a time difference between time  $\Delta t$  and  $\Delta t'$  recorded by  $T_c$  and  $T_d$  that is induced by electric potential  $\varphi$ , and  $\Delta t < \Delta t'$ . Comparing the measured values and the values calculated by equation (117) will verify the theory. If the experiment proves that the theoretic calculation is correct, then from the experiment data, the magnitude of the electric potential limit  $\Phi_0$  can be obtained by the equation:

$$\Phi_0 = \frac{\Phi}{\sqrt{1 - \frac{\Delta t^2}{\Delta t'^2}}} \tag{130}$$

It would be extremely difficult to achieve very high electric potential  $\varphi$  in the laboratory. However, the advantage of this experimental setup is that through adding the experimental time and improving the accuracy of the time measurement, it lowers the required the electric potential and increases the possibility of success in the experiment. Base on the theory of electrodynamic space-time relativity, many new physical effects can be derived, which in turn, can prove the validity of the theory through experiments based on the said effects.

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# Appendix A:

Theoretical verification of the fundamental equations of the theory of electrodynamic space-time relativity

(For definitions of symbols, please refer to refer to the above paper, "the theory of electrodynamic space-time relativity")

From the postulate of the theory of electrodynamic space-time relativity, the norm-modulus limit of the quaternion velocity is the speed of light  $C_0(299,792,458 \text{ m/sec})$  in vacuum in reference system with zero electric potential. In addition, it is unrelated to the quaternion velocity of the reference frame.

Let there be two events that occur in the reference frame  $\Sigma_Q(X,Y,Z,F,t)$  with zero quaternion velocity. Event A emits a signal at the coordinate origin  $Q_0(0,0,0,0,0)$  of the reference frame, and Event B receives the signal at another point Q(X,Y,Z,F,t) of the reference frame. The space-time interval between the two events can be defined as S:

$$S^{2} = X^{2} + Y^{2} + Z^{2} + F^{2} - C_{0}^{2}t^{2}$$
 [a.1]

The norm-modulus of quaternion distance  $R_q$  in the theory of electrodynamic space-time relativity is  $||R_q||$ , where  $||R_q||^2 = X^2 + Y^2 + Z^2 + F^2$ 

Observing the same two events in reference frame  $\Sigma_Q'(X',Y',Z',F',t')$  with quaternion velocity  $V_q$ , the coordinate points  $Q_0$  and Q in the reference frame  $\Sigma_Q$  now become  $Q_0'$  and Q' in reference frame  $\Sigma_Q'$ . Let the two coordinate origins  $Q_0'$  and  $Q_0$  overlap, the two events' coordinates are  $Q_0'(0,0,0,0,0)$  and Q'(F',X',Y',Z',t'). And the space-time interval between the two events is now defined as S'

$$S'^{2} = X'^{2} + Y'^{2} + Z'^{2} + F'^{2} - C_{0}^{2}t'^{2}$$
 [a.2]

The norm-modulus of quaternion distance  $R'_q$  in the theory of electrodynamic space-time relativity is  $||R'_q||$ , where  $||R'_q||^2 = X'^2 + Y'^2 + Z'^2 + F'^2$ 

Based on references [1] and [2] which discusses theory of special relativity, using the same methods, it can be proven that the space-time interval does not change with the change in the frame of reference. Hence  $S'^2 = S^2$ . Then

$$X'^{2} + Y'^{2} + Z'^{2} + F'^{2} - C_{0}^{2}t'^{2} = X^{2} + Y^{2} + Z^{2} + F^{2} - C_{0}^{2}t^{2}$$
[a.3]

The above equation can be expressed in terms of the norm-modulus of quaternion.

$$||R'_{q}||^{2} - C_{0}^{2}t'^{2} = ||R_{q}||^{2} - C_{0}^{2}t^{2}$$
[a.4]

Its physical meaning is that the norm-modulus  $C_0$  of quaternion velocity limit is invariant. It is one of the mathematical expression of the basic postulates of the theory of electrodynamic space-time relativity. When potential difference is zero between the two reference frames, that is F' = F, it becomes the equation of the principle of invariant light speed in the special theory of relativity. For the sake of simplicity, the above equation can be expressed as

$${r'}^2 + {F'}^2 - {C_0}^2 {t'}^2 = r^2 + F^2 - {C_0}^2 t^2$$
 [a.5]

Where

$${r'}^2 = X'^2 + Y'^2 + Z'^2$$
 [a.6]

$$r^2 = X^2 + Y^2 + Z^2 ag{a.7}$$

Below are the fundamental quaternion equations of the theory of electrodynamic space-time relativity (for its derivation steps and also definition of physical quantities please refer to the 1<sup>st</sup> paper).

$$R_{q}' = R_{q} - \frac{V_{q}}{||V_{q}||} ((1 - \gamma)r_{1} + ||V_{q}||\gamma t)$$
[a.8]

$$t' = \gamma \left( t - \frac{||V_q||}{C_0^2} r_1 \right) \tag{a.9}$$

Where.

$$\gamma = \frac{1}{\sqrt{1 - \frac{||V_q||^2}{{c_0}^2}}}$$
 [a.10]

$$r_1 = \frac{1}{||V_q||} (FV_{\phi} + XV_X + YV_Y + ZV_Z)$$
 [a.11]

Separate equation [a.8] into a vector equation [a.12] and an imaginary equation[a.13],

$$\mathbf{r}' = \mathbf{r} - \frac{\mathbf{v}_{\mathbf{r}}}{||\mathbf{v}_{\mathbf{q}}||} ((1 - \gamma)\mathbf{r}_{1} + ||\mathbf{v}_{\mathbf{q}}||\gamma\mathbf{t})$$
 [a.12]

$$F'i = Fi - \frac{\dot{V}_{\phi}i}{||V_{\alpha}||} \left( (1 - \gamma)r_1 + ||V_{\alpha}||\gamma t \right)$$
 [a.13]

Inequation [a.12], the direction of the three vectors  $\mathbf{r}'$ ,  $\mathbf{r}$  and  $\mathbf{V}_{\mathbf{r}}$  are the same. Hence it can be converted to a scalar equation.

$$r' = r - \frac{V_r}{||V_q||} \left( (1 - \gamma)r_1 + ||V_q||\gamma t \right)$$
 [a.14]

Where.

$$||V_{q}||^{2} = V_{r}^{2} + V_{\Phi}^{2}$$

$$V_r^2 = V_X^2 + V_Y^2 + V_Z^2$$

$$V_r = V_X \frac{V_X}{V_r} + V_Y \frac{V_Y}{V_r} + V_Z \frac{V_Z}{V_r}$$

Since vector  $\mathbf{V_r}$  and vector  $\mathbf{r}$  have the same direction, therefore  $\frac{V_x}{V_r} = \frac{X}{r}$ ,  $\frac{V_y}{V_r} = \frac{Y}{r}$ ,  $\frac{V_z}{V_r} = \frac{Z}{r}$ , Then from equation [a.7] the below equation can be obtained.

$$r = X\frac{v_X}{v_r} + Y\frac{v_Y}{v_r} + Z\frac{v_Z}{v_r}$$

Divided both sides of equation [a.13] by i, then the equation becomes the following,

$$F' = F - \frac{V_{\phi}}{||V_{q}||} \left( (1 - \gamma) r_{1} + ||V_{q}|| \gamma t \right)$$
 [a.15]

Let 
$$A = ((1 - \gamma)r_1 + ||V_q||\gamma t)$$
 [a.16]

Substituting equation [a.16] into [a.14] and [a.15], and then substitute [a.14] and [a.15] into equation [a.5], then

$$\begin{split} &r'^2 + F'^2 - (C_0 t')^2 = \left(r - \frac{V_r}{||V_q||}A\right)^2 + \left(F - \frac{V_\varphi}{||V_q||}A\right)^2 - \left(C_0 \gamma \left(t - \frac{||V_q||}{C_0^2}r_1\right)\right)^2 \\ &= r^2 - \frac{2rV_r}{||V_q||}A + \left(\frac{V_r}{||V_q||}A\right)^2 + F^2 - \frac{2FV_\varphi}{||V_q||}A + \left(\frac{V_\varphi}{||V_q||}A\right)^2 - \left(C_0 \gamma \left(t - \frac{||V_q||}{C_0^2}r_1\right)\right)^2 \\ &= r^2 + F^2 - \frac{2(XV_X + YV_Y + ZV_Z + FV_\varphi)}{||V_q||}A + \frac{A^2}{||V_q||^2}\left(V_r^2 + V_\varphi^2\right) - \left(C_0 \gamma \left(t - \frac{||V_q||}{C_0^2}r_1\right)\right)^2 \\ &= r^2 + F^2 - 2r_1A + A^2 - \left(C_0 \gamma \left(t - \frac{||V_q||}{C_0^2}r_1\right)\right)^2 \end{split}$$

$$\begin{split} &= r^{2} + F^{2} + A(A - 2r_{1}) - \left(C_{0}\gamma\left(t - \frac{||V_{q}||}{C_{0}^{2}}r_{1}\right)\right)^{2} \\ &= r^{2} + F^{2} + \left(||V_{q}||\gamma t - \gamma r_{1} + r_{1}\right)\left(||V_{q}||\gamma t - \gamma r_{1} - r_{1}\right) - \left(C_{0}\gamma\left(t - \frac{||V_{q}||}{C_{0}^{2}}r_{1}\right)\right)^{2} \\ &= r^{2} + F^{2} + \left(||V_{q}||\gamma t - \gamma r_{1}\right)^{2} - r_{1}^{2} - \left(C_{0}\gamma\left(t - \frac{||V_{q}||}{C_{0}^{2}}r_{1}\right)\right)^{2} \\ &= r^{2} + F^{2} + ||V_{q}||^{2}\gamma^{2}t^{2} - 2||V_{q}||\gamma^{2}tr_{1} + \gamma^{2}r_{1}^{2} - r_{1}^{2} - C_{0}^{2}\gamma^{2}t^{2} + 2\gamma^{2}t||V_{q}||r_{1} - \frac{||V_{q}||^{2}}{C_{0}^{2}}\gamma^{2}r_{1}^{2} \\ &= r^{2} + F^{2} - C_{0}^{2}t^{2}\gamma^{2}\left(1 - \frac{||V_{q}||^{2}}{C_{0}^{2}}\right) + r_{1}^{2}\gamma^{2}\left(1 - \frac{||V_{q}||^{2}}{C_{0}^{2}}\right) - r_{1}^{2} \\ &= r^{2} + F^{2} - C_{0}^{2}t^{2} \end{split}$$

In conclusion, the fundamental equations of the theory of electrodynamic space-time relativity are consistent with its hypothesis. The mathematical derivation and logics of this theory should also be correct. In addition, because the theory of complex electrodynamic space-time relativity (TCESTR), the theory of electric potential relativity (TEPR) and the special theory of relativity (STR) are all special case of the theory of electrodynamic space-time relativity, their fundamental equations are also proven to be consistent with the fundamental hypothesis.

- [1] Albert Einstein, *Relativity, The Special and the General Theory (A Popular Exposition)*, Beijing Press, January 2006, P91-95
  - [2] Shuohong Guo, Electrodynamics, 3rd edition, Beijing Higher Education Press, Jun 2008. P192-196

<sup>\*\*</sup> The revised version 4 of the paper, the theory of electrodynamic space-time relativity, The main modification work has been completed for a long time. The main revisions of this version are: the deletion of the foreword; description of the correspondence between potentials and imaginary speed; further simplification of the "system time"; the basic equation becomes the most concise form (as in the Galileo transformation form, but the content is more profound, covers more extensively; added a mathematical validation appendix. However, the content of the core of the paper has not changed like the earlier version.